

# MINI-LAB ROBOTICS EDUCATIONAL KIT

The best trade-off between robustness and economic competitiveness.

The Mini-Lab is suitable for advanced research in robotics whether in the low-level programming or in higher-level indoor applications like path planning, tracking, surveillance, monitoring... It is the adequate test-bed for researchers to implement different algorithms using data from numerous sensors.

SOLID ALUMINUM
CHASSIS POWERED BY HIGH
TOROUE MOTORS

WI-FI CONNECTIVITY

HARDWARE ABSTRACTION WITH ROS ARCHITECTURE

**:::** ROS.org

LOW LEVEL SENSORS
INTERFACE WITH ARDUINO

COMPLETE WIKI PAGES AND WORKSHOPS

LABS CAN BE SIMULATED ON BOTH MATLAB AND GAZEBO







RODOTS FOR CHANGING THE WORLD...



## **TECHNICAL SPECIFICATIONS**

#### Mechanical

Dimensions ( $W \times L \times H$ )

Weight

Load Capacity

Speed

Max slope Angle

Power

Battery Autonomy

On-board voltage

409×364×231

11.5 Kg 3 Kg

1.5 m/s

10°

12 V

5V / 12V

4h

**Electronics** 

Processor Sensor interface Depth Camera

Sensors

Atom N2800

Arduino compatible Asus Xtion Live Pro (x5) Ulrasonic sensor

(x5) Ulrasonic sensor (x5) Infra-Red sensors

Communication

Wireless

Extension with

IEEE 802.11b/g/n -

USB, Ethernet

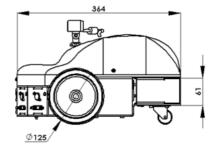
## **OPTIONS**

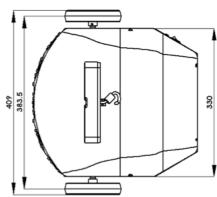
Hokuyo Laser

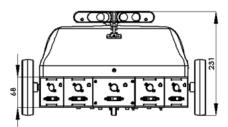


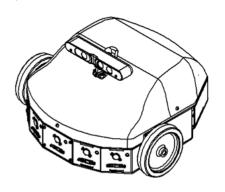
Docking Station













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